ADAM WELD

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OBJECTIVE - Seeking a full time position in R&D working on challenging multidisciplinary projects. I thrive on fast iteration and outside-of-the-box thinking. Most interested in areas that synthesize of one or more of electronics, mechatronics, embedded systems, machine learning, and computer vision, and motion control.

EDUCATION

Cornell University B.S. in Electrical and Computer Engineering - May 2019

0 0 0	Electrical ☐ Schematic design and simulation, validation ☐ PCB layout and routing ☐ Digital and analog RF communications ☐ Microcontrollers and embedded systems				chanical SolidWorks modeling Materials properties, selection and testing Design for manufacture Statics and Dynamics Ansys FEA simulation Precision Tolerancing	0	Programming in C, C++, Python, MATLAB, BASH High Level design and subsystem integration Actuators, manipulators, sensors, and drivetrain Control algorithms	000000	Anufacturing Supply Chain / OEMs CNC milling/waterjet Rapid Prototyping 3D Print / Laser Cut Injection molding Precision soldering SMD reflow/rework
PROFESSIONAL EXPERIENCE									
10.2016 - Present Seattle, WA			Launched drone company with industry-leading performance in ultralight racing market. Lead Research and Development on custom BLDC motors, Carbon Fiber Exoskeleton design, STM32-based flight control electronics, LIDAR subsystem, flight testing and qualification. Achieved best-in-class noise performance, durability, safety, wind resistance, size and weight. Coordinated manufacturing logistics, distribution, marketing, and customer support.						
Amazon Prime Air 05.2017 - 09.2017 Seattle, WA Hardware Design Internship		000 0 0	Took ownership of flight critical sensor subsystem and researched dozens of white papers. Worked with team members and leadership to identify areas needing improved performance. Created test plans, physical rig and fixturing, and scripting to document the precision and accuracy of numerous possible replacement sensors and characterize their behavior. Designed a densely populated six-layer printed circuit board in Altium from schematic to layout using integrated ECAD/MCAD techniques, and performed board bring-up and testing. Engineered and manufactured a weather-sealed enclosure for subsystem.						
Vantage Robotics 05.2016 - 08.2016 SF Bay Area, CA Hardware Design Internship		000 00	Designed and tested PCB with FTDI and pogo-pin interface for debugging and development. Fabricated programming, manufacturing, and assembly jigs for production with CM / OEM. Created three-axis ball bearing test stand with .01 degree repeatability to calibrate camera firmware and digital image stabilization algorithm. Redesigned components for manufacturability and cost reduction. Prototyped WiFi repeater handset and implemented video pass through functionality.						
05.2015 - 09.2015 Seattle, WA Hardware Design		0 0 0	Designed electromechanical positioning subsystem for an electron microscope, from conceptualization to the fabrication of a working production prototype. Gained experience in vacuum systems and cleaning procedures and materials selection. Modeled and simulated precision flexure assembly for EDM machining out of Titanium. Designed, built, and tested custom nanoscale piezoelectric linear actuators and prototyped precision four-axis linear motion system.						
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PROJECTS AND CLUBS

04.2013 - 03.2014

Robotics and State

Estimation Research

Seattle, WA

Researched and helped implement (in ROS) visual object recognition, semantic world

☐ Incorporated real time video, RGBD cameras, and laser scanning technologies into feedback

sensor placement, and connecting structure architecture.

and controls structure.

knowledge system and natural language processing programs.